The muscle silent period and reciprocal inhibition in man

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SUMMARY The mechanical properties of muscle are shown to have a significant influence on the duration of the silent period in the soleus EMG. In contrast to this, the mechanical events have no influence on the duration of the reciprocal inhibition of the anterior tibial muscle. However, a second, delayed cessation of the EMG activity in the anterior tibial muscle is due to mechanical events.

The muscle silent period which follows a twitch contraction, found in the electromyogram (EMG) of man by Hoffmann (1922) is a phenomenon related to several reflex mechanisms which include both direct inhibition of the motoneurone pools and the simultaneous withdrawal of afferent muscle spindle facilitation (Hoffmann, 1922; Merton, 1951; Granit, 1955; Paul, 1955; Hufschmidt, 1966). The electrical silence of reciprocal inhibition of the antagonist muscle is produced by different mechanisms (Sherrington, 1906; Creed, Denny-Brown, Eccles, Liddell, and Sherrington, 1932; Granit, 1955). Reciprocal inhibition has been demonstrated in cats (Lloyd, 1943) and Hagbarth (1962) and Liberson (1965) have shown its probable presence in man at high stimulus intensities.

In a recent paper (Gottlieb and Agarwal, 1971) we discussed the effects of the voluntary contraction of a stimulated muscle and of its antagonist on the Hoffmann reflex (Hoffmann, 1922). It was shown that the relationship between the amplitude of the electromyographic (H-wave) and mechanical (twitch) components of the Hoffmann reflex may be significantly influenced by the silent period in the agonist muscle and by reciprocal inhibition in the antagonist muscle. The presence of reciprocal inhibition in the anterior tibial muscle with low level stimulation of the tibial nerve was clearly demonstrated. In the present paper we shall discuss the influence of voluntary contraction on both the silent period and on reciprocal inhibition.

METHODS

Our experiments were performed on five normal male adults ranging in ages from 21 to 36 years. A subject was seated normally in a chair with his right leg extended, the knee slightly flexed and the foot strapped to a fixed plate with an attached strain gauge bridge for measuring isometric torque. The signal from this bridge was also used to provide a visual reference to help the subject maintain a constant foot torque before stimulation. Differential EMG surface electrodes (1 cm diameter) were placed on the centre-line of the lower soleus muscle about 3 cm apart and 20 cm above the base of the foot, and another pair was placed on the anterior tibial muscle. A ground electrode was placed over the flat surface of the tibia. Cutaneous stimulating electrodes were located posteriorly over the tibial nerve in the popliteal fossa and anteriorly just above the knee. These were held in place by Velcro straps. All electrodes were coated with Sanborn Redux Creme. The electrical stimuli of 1·5 msec duration were applied from a Grass S-8 stimulator through an SIU5 isolation unit.

RESULTS

Figures 1 and 2 show characteristic patterns of the muscle silent period. Figure 1a shows the silent period in the EMG of the soleus muscle and the resulting twitch at an initial foot torque (IFT) level of 0·9 kgm in plantarflexion. The stimulus is a pure H-reflex and is shown on a different time scale. Figure 1b shows the silent

1 The aluminium foot plate is rigid. However, the contraction is not perfectly isometric for the elasticity of the muscle and tendon permit a small amount of shortening. It is safe to assume, however, that the relationship between measured torque and muscle tension remained constant and linear during a muscle contraction.
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FIG. 1a. Silent period in the soleus muscle after the H-wave. Plantar IFT level 0.9 kg m. Five traces superimposed. H-wave 0.8 mV/unit at 5 msec/unit time scale, soleus EMG 0.04 mV/unit, twitch torque 0.47 kg m/unit, time 50 msec/unit.

FIG. 1b. Silent period in the soleus muscle after the H-wave. Top trace in each of the three responses is the soleus EMG, 0.1 mV/unit. Lower trace is the twitch torque, 1.2 kg m/unit, at three levels of plantar initial foot torque (IFT) 0.9, 1.8, and 2.7 kg m, IFT increasing from top to bottom, time 50 msec/unit.

FIG. 2a. Silent period in the soleus muscle after a strong H-wave at IFT level of 4.5 kg m. Five traces superimposed. Soleus EMG 0.04 mV/unit, twitch torque 0.47 kg m/unit, time 50 msec/unit.

FIG. 2b. Silent period at two levels of plantar IFT 0.47 and 1.1 kgm. Twitch torque 1.2 kg m/unit, soleus EMG 0.04 mV/unit, time 50 msec/unit.

Period in the soleus EMG and the resulting twitch at three different levels of IFT in plantar-flexion. In this Figure, the IFT is increasing from top to bottom and the stimulus is pure H-reflex. Quite clearly, the break in the silent period occurs after the twitch peak and before the hump in the relaxation phase of the twitch (Creed et al., 1932). Some individual motor units may fire earlier, during the silent period, particularly at higher levels of IFT. This earlier activity within the silent period can indeed be very significant with strong IFT (see Figs 1b and 2a). The silent period and the subsequent EMG activity in the soleus is strongly influenced by the time course of the mechanical events—that is, by the muscle twitch. In Fig. 2b, an increase in IFT causes the relaxation phase of the twitch to occur sooner and more rapidly, resulting in a briefer silent period.

Figures 3 and 4 show characteristic patterns of reciprocal inhibition in the anterior tibial muscle. The foot is dorsiflexed by the subject. The IFT in Fig. 3a is 1.92 kg m and the stimulus is near maximal for the H-wave. In Fig. 3b the stimulus
elicits a near maximal M-wave. Figure 4 shows the EMG activity in the anterior tibial muscle during strong dorsal IFT and with a near maximal M-wave stimulus.

As the foot is more strongly plantarflexed (with the stimulating voltage held constant), the twitch produced by a reflex diminishes (Gottlieb and Agarwal, 1971). There are other changes that may also be observed in the electrical and mechanical behaviour of this twitch. The twitch contractions at three different levels of IFT are superimposed in Fig. 5. The twitch peak occurs earlier as plantar IFT increases as does the hump in the relaxation phase (Agarwal, Berman, Löhnenberg, and Stark, 1970). It is also true that as IFT increases in plantarflexion, the peak-to-peak amplitude of the H-wave increases (Paillard, 1955; Gottlieb and Agarwal, 1971). The H-wave amplitude influences more than just the twitch amplitude, for, with increased H-wave amplitude, the twitch peak time is reduced by about 20 msec (Buchthal and Schmalbruch, 1970).

In Fig. 1b the decrease in the duration of the silent period with increasing IFT is as much as 50 msec and is consistently seen in all subjects.
The cessation of the silent period by a burst of EMG activity during the relaxation phase of the muscle is a mechanically induced event due to restretching of the primary endings of the spindles (Granit, Kellerth, and Szumski, 1966).

The strong mechanical influence of the twitch on the EMG is further shown in Fig. 2b, where a short, second silent period is observed with a clonus-like EMG (Rabending and Koch, 1962). In this Figure, the IFT level is nearly doubled for the lower trace, significantly changing the duration of the silent period as well as subsequent EMG activity.

**DISCUSSION**

The pause in the discharge of the spindle primaries during contraction has been accepted as the decisive factor in the explanation of the silent period ever since the work of Fulton and Pi-Suñer (1928), Matthews (1933), Granit and Van der Meulen (1962), Jansen and Rudjord, 1964, and Angel, Eppler, and Iannore (1965). Granit and Van der Meulen (1962) have observed that the duration of the pause of the primaries in contraction varies very little with passive tension and extension. However, the mechanical events in an actively contracted muscle are quite different from those in one that is passively stretched.

These results clearly indicate that the duration of the silent period in man depends on the level of the initial muscle activity. They are consistent with the experiments of Merton (1951), Paillard (1955), and Liberson (1962). However, they are in contradiction to a recent study by Higgins and Lieberman (1968 a, b).

There are, of course, several other factors contributing to the generation of the silent period: Golgi tendon organ inhibition, Renshaw cell inhibition, and the synchronizing effect of simultaneous discharge of the alpha motoneurone pool (Hoff, Hoff, Bucy, and Pi-Suñer, 1934). Although the sensory contributions (spindle and tendon organ) will influence the duration of the silent period, the initiation of the silent period, which immediately follows the H-reflex, must be brought about by the other, purely spinal, phenomena. (The effect of other group I fibres that may be excited by the stimulus is presumably inhibitory but is not accurately known.) That is because the peripheral sensory response cannot begin until the appearance of the H-wave (which initiates the reflex contraction), and the sequela cannot be manifest in the EMG for the 30 msec it takes for information to circumnavigate the reflex arc. The immediate spinal effects of a synchronized motor discharge are a hyperpolarization of recently fired motoneurones which is reinforced by an inhibitory volley from the Renshaw cells. In the example in Fig. 6 the gastrocnemius-soleus muscle group is contracting rapidly at the time when the H-reflex is elicited. The strong EMG activity continues during the interval between the electrical stimulus and the H-wave, and is suddenly interrupted for a period of about 25–30 msec. Because of the vigorous voluntary contraction, there is no effective twitch but a brief inhibition is still produced by spinal mechanisms alone.

Whereas the duration of the silent period is related to contractile events and is terminated by an EMG burst due to restretching of the spindles, the observed duration of reciprocal inhibition (about 30 msec) is independent of muscular activity and remains constant with changes of IFT in dorsiflexion. The inhibition appears from the instant that the H-wave is observed in the soleus muscle. This time of onset is unaltered even when the stimulus is large enough to block antidromically the H-wave in the soleus muscle. This constancy occurs because reciprocal inhibition is due to the orthodromic Ia fibre volley in the tibial nerve which inhibits the motoneurone pool of its antagonist muscle. The duration of this inhibition is comparable with that
appearing in the contracting soleus muscle in Fig. 6. Such a similarity is not unexpected since both silences are produced by spinal rather than peripheral influences.

An interesting observation in relation to reciprocal inhibition in the anterior tibial muscle may be made in Fig. 4. A 50 msec pause in the EMG activity is observed at the hump in the twitch, induced by the mechanical events of that twitch. Just before the hump, the gastrocnemius-soleus muscle is in its relaxation phase which permits restretching of the gastrocnemius-soleus spindles. The induced activity in afferent Ia nerve fibres from the gastrocnemius-soleus primary spindle endings has an inhibitory influence on the motoneurone pool of the anterior tibial muscle. At the same time the spindles of the anterior tibial muscle are shortening. These two factors together produce the observed cessation of the EMG activity in the anterior tibial muscle.

Excitation of primary spindle afferent fibres from the gastrocnemius and soleus muscles may produce a period of electrical silence on both homonymous and antagonistic muscle groups. The silence of the antagonist is due to reciprocal inhibition over neural pathways within the spinal cord. The homonymous silence is also initiated by spinal mechanisms but the extended duration of this silence is determined by mechanical factors of the contracting muscle.

This work was partially supported by NSF grant GK-17581 and NIMH grant MH-8396.

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*J Neurol Neurosurg Psychiatry* 1972 35: 72-76
doi: 10.1136/jnnp.35.1.72

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